Miniaturized humidity and temperature sensing RFID enabled tags

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Abstract
A compact 27-bit linearly polarized chipless radio frequency identification tag is presented in this research. The proposed tag is designed with an overall tag dimension of 23 × 23 mm². The tag comprises of metallic (copper) rings-based structure loaded with slots. These slots correspond to a particular sequence of bits. The circular tag is analysed using 2 different substrates, that is, Rogers RT/duroid/5870 and flexible Rogers RT/duroid/5880. The radar cross-section response of frequency signatured tag is analysed for humidity and temperature sensor designs. Humidity sensing is achieved by deploying a DuPont Kapton HN heat resistant sheet on the shortest slot of the tag, that is, the sensing slot. Temperature sensing is attained using Rogers RT/duroid/5870 and Stanyl polyamide as a combined substrate. Hence, the miniaturized, robust, and flexible tag can be deployed over irregular surfaces for sensing purposes.

KEYWORDS
chipless tag, electromagnetic, flexibility, humidity sensor, temperature sensor

1 | INTRODUCTION

Internet of things (IoT) also known as ambient intelligence is an emerging technology. It ensures connectivity of physical and virtual objects to the internet at an unprecedented rate, thus, transforming traditional objects into smart ones.¹,² This technology is an integral part of internet future, and it will interconnect uniquely identified embedded items through ubiquitous communication of physical objects.³,⁴ IoT uses wireless and pervasive computing technologies to make objects intelligent.¹,⁵

The idea of IoT can be implemented using radio frequency identification (RFID) technology. RFID is a promising technology which has revolutionized automatic identification and wireless sensing of tagged objects.⁶ RF waves are exchanged between a tag and reader using wireless transmission. RFID is a fairly handy technology because it facilitates non-line of sight communication which improves the tag’s efficiency and provides longer reading range.⁷–⁹ At the item level tracking, RFID technology is replacing optical barcodes.⁷

The fabrication of microchip circuits is really expensive, and this sets a certain limitation on the manufacturing of RFID tags. This problem can be solved by excluding the microchip from the tag design. RFID tag without silicon chip is famous as chipless RFID tag.¹⁰–¹² Chipless tags have already gained attention due to the removal of microchips from the circuitry and are aimed to further drive the costs down using techniques such as ‘inkjet printing’. Other than low-cost expectations, these tags ensure stronger robustness, long read range and advanced real-time performance,
avoiding delays.\textsuperscript{13} In chipless RFID tags, an integrated circuit (IC) and self-empowerment are not required; hence, these tags do not utilize transmission protocols for detection.\textsuperscript{14} The data are encoded using electromagnetic (EM) waves instead of the ICs (which are expensive). The tag is excited by EM waves, and the encoded backscattered signal is received by the reader. The tag responses can be analysed in the time domain or the most commonly used frequency domain.\textsuperscript{15,16}

The chipless RFID tags are further examined to make the tag capable of performing sensor functions.\textsuperscript{17} Various researches have been made in the field of chipless RFID tags with integrated sensors. In Ref. 18, a poly-vinyl alcohol (PVA)-based humidity sensor is presented. In this article, the RH sensing is first done using PVA dielectric film and in addition to this, the sensing behaviour is also realized using Kapton HN polymer. A comparative analysis is drawn between the 2 techniques.

In Ref. 19, a 30-bit tag, incorporating an additional feature of temperature sensing is presented. In this work, Stanyl polyamide resin is used for temperature sensing. The Stanyl polymer is placed beneath the 2 innermost slots of the tag, which ultimately detects the temperature change.

This research article presents a passive, high capacity, chipless RFID tag. The 27-bit circular shaped tag with opened slots is capable of storing a large amount of data while remaining in a compact tag size of $23 \times 23 \text{ mm}^2$. The metal portion in the tag design corresponds to the capacitive part, whereas, the slots represent the inductive element. The combination of binary numbers is generated using slot/resonator structure. Each slot is responsible for yielding ‘1’ bit and the metal portion generates ‘0’ bit. Hence, in this way, the data are encoded in the proposed tag.

The linearly polarized tag design is realized for rigid (Rogers RT/duroid/5870) as well as flexible (Rogers RT/duroid/5880) substrate. The frequency band for Rogers RT/duroid/5870 is 3.3–13.5 GHz, whereas, the operational spectrum for flexible Rogers RT/duroid/5880 is 3.5–14.0 GHz. The flexible characteristic of the tag makes it suitable to be deployed on a variety of objects, for example, the irregular curvatures of bottles.

Furthermore, the effectiveness of the tag is enhanced by adding the sensing attribute. Humidity sensing trait is attained by deploying DuPont Kapton HN heat resistant tape on the shortest slot that corresponds to the least significant bit (LSB). The feature of temperature sensing is achieved with the aid of polyamide resin that is temperature dependent. Hence, data dense, finite-sized, flexible, sensor integrated, the low-cost tag is proposed. The novelty of the proposed tag design relies on high data storage capacity, flexibility, and sensor integration in smaller tag size as compared to the already proposed work as shown in Table 1.

The basic arrangement of the research article is as follows: section 2 introduces the working principle of the tag. Section 3 includes the structure and relative dimensions. Section 4 is the major section with 2 subsections. It starts with the discussion of the results achieved. The first part explains humidity sensing while the other one covers the temperature sensing. The proposed research article is concluded in section 5.

2 WORKING PRINCIPLE

The basic working principle of chipless RFID tag is based on backscattering phenomena; similar to that used by conventional pulsed radars. The backscattering operation is shown in Figure 1\textsuperscript{22} which consists of a reader also known as ‘interrogator’ and a chipless RFID tag additionally known as ‘transponder’.

The reader is used to activate and hear the tag. It basically consists of 2 main components which include a vector network analyser (VNA) and the antenna subsystem. VNA performs 2 core functions, that is, generation of the signals to be transmitted and the detection of the signals that are reflected back towards the reader. Antenna subsystem is used for the production of the polarized signals. It also performs the functions of transmitting and receiving of the signals.\textsuperscript{23} The reader transmits an EM wave. If the chipless tag is present in the vicinity of the reader, it absorbs the transmitted EM waves which stimulate a current on the metallic surface of the tag. As a result, a modulated wave is generated that is scattered back towards the reader. This wave is known as backscattered signal, which contains the encoded data.\textsuperscript{24} The unique tag’s ID is used for the identification of the received information.

The radar cross-section (RCS) response of the tag is measured at Fraunhofer far-field distance that can be calculated by Equation 1.

\[
R = \frac{2D^2}{\lambda} \quad (1)
\]

Here, $R$ is the far-field distance, $D$ is the largest dimension of the tag, and $\lambda$ is the wavelength.\textsuperscript{25}

The receiving antenna collects the power that is broadcasted by the transmitting antenna. This transmitted power is given by Friis transmission equation,\textsuperscript{26}

\[
\frac{P_{RX}}{P_{TX}} = \left(\frac{\lambda}{4\pi r}\right)^2 G_{TX}G_{RX} \quad (2)
\]

Where the distance between transmitter and receiver is referred as $r$, $G_{TX}$ is the gain of the transmitter antenna and $G_{RX}$ is the gain of receiver antenna, $\lambda$ is the wavelength,
$P_{TX}$ and $P_{RX}$ are the transmitted and received power, respectively.

The chipless RFID tags can be excited by a linearly or dual polarized EM waves. The incident plane wave is mathematically given as,

$$E(x, y, z, t) = E_0 \exp \left[ j(\omega t - kz) \right] \hat{x} + E_0 \exp \left[ j(\omega t - k \hat{z} + \pi/2) \right] \hat{y}$$

(3)

where $E$ is an electric field, $\omega$ is angular frequency, $k$ is wave vector, $t$ represents time, and, $(x, y, z)$ is position vector.

The chipless RFID tag, presented in this research article, is excited by a linearly polarized incident plane wave. The tag is composed of slot/resonator structure where each slot generates ‘1’ bit. Hence, in this way multiple bits can be accumulated within the tag’s structure without the need of an application specific integrated circuit.[27]

### TABLE 1  Comparison with other chipless RFID tags

<table>
<thead>
<tr>
<th>Resonator shape</th>
<th>Circular (proposed research)</th>
<th>U-shaped$^6$</th>
<th>Circular$^{20}$</th>
<th>Hexagonal$^{21}$</th>
<th>Rectangular$^7$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tag Size (mm$^2$)</td>
<td>23 $\times$ 23</td>
<td>26 $\times$ 70</td>
<td>153.8</td>
<td>23 $\times$ 10</td>
<td>15 $\times$ 6.8</td>
</tr>
<tr>
<td>No. of bits</td>
<td>27</td>
<td>20</td>
<td>9</td>
<td>14</td>
<td>6</td>
</tr>
<tr>
<td>Bit density (bit/cm$^2$)</td>
<td>5.1</td>
<td>1.09</td>
<td>5.8</td>
<td>6.08</td>
<td>5.8</td>
</tr>
<tr>
<td>Flexibility</td>
<td>✓</td>
<td>x</td>
<td>✓</td>
<td>x</td>
<td>✓</td>
</tr>
<tr>
<td>Sensing</td>
<td>✓</td>
<td>x</td>
<td>✓</td>
<td>x</td>
<td>✓</td>
</tr>
<tr>
<td>RCS max (dBsm)</td>
<td>$-23 \sim -35$</td>
<td>$-31 \sim -40$</td>
<td>$-6 \sim -14$</td>
<td>$-25 \sim -31$</td>
<td>$-29 \sim -31$</td>
</tr>
</tbody>
</table>

3 | CHIPLESS RFID TAG DESIGN

A compact, highly dense chipless RFID tag is presented in Figure 2. The tag structure resides in a miniature footprint of 23 $\times$ 23 mm$^2$ and the total diameter of the circular patch is 21 mm.

The proposed tag is realized on 2 different substrates, that is, Rogers RT/duroid/5870 having a thickness of 0.78 mm ($\varepsilon_r = 2.2$) and Rogers RT/duroid/5880 flexible with a thickness of 0.508 mm ($\varepsilon_r = 2.2$). The radiator is designed using a copper cladding having a thickness of 35 $\mu$m. The circular shaped design is composed of an arrangement of slots/resonators where each slot corresponds to a bit. The length and width of each slot are varying to make it resonant at a different frequency. Hence, there are 27 slots corresponding to 27 bits generating $2^{27} = 134,217,728$ exclusive Auto-IDs having a bit density of 5.1 bit/cm$^2$. The widths of the slots are given in Table 2.

A circle of diameter 10.8 mm is designed in the centre of the tag to achieve sharper resonances. According to the
operation of chipless RFID tags, the longest slot provides the
dip at the lowest frequency and is known as a most signifi-
cant bit while the shortest slot identified as a LSB gives the
resonance at the highest frequency. The varying lengths and
widths of the slots allow the resonances to be produced at
different frequencies.

The resonating frequency of the slot of a particular radius
can be determined by the mathematical relation given below,

\[ f_{res} = \frac{c}{2\pi R_{slot}} \sqrt{\frac{2}{\varepsilon_r + 1}} \]  \hspace{1cm} (4)

Here, \( R_{slot} \) represents the radius of the slot, \( \varepsilon_r \) shows the
relative permittivity of the substrate used, and \( f_{res} \) is the
resonating frequency of the slot.\(^{25}\) Thus, the above-given
equation shows that a distinct slot, resonating at a particular
frequency relies on the radius of that slot and the relative
permittivity of the substrate.

The designing, simulation, and optimization of the intro-
duced tag are performed on CST Microwave Studio Suite.
Incident plane wave is used for exciting the tag.

4 RESULTS AND DISCUSSION

The tag proposed in this work is capable of generating \( 2^{27} \)
unique bit sequences in a small size. The fabricated tag is
scrutinized in a real environment to achieve measured results.

The measurement setup is same as that in Ref. 28, utiliz-
ing a combination of transmitting and receiving horn anten-
as, VNA model R&SZVL13 and the prototype of the tag
under test. In the proposed research, the far-field distance is
taken as 30.2 mm at which the tag is placed to measure the
RCS response.

The 27-bit tag, representing a bit word ‘11111111111111
11111111111111’, presented in this research article, is
optimized for 2 different substrates. Figure 3A shows the
RCS response of the tag analysed on Rogers RT/duroid/5870
substrate and is named as ‘Tag-A’. The results for ‘Tag-B’
are shown in Figure 3B in which copper radiator is etched on
Rogers RT/duroid/5880 flexible substrate. The characteristic
comparison of 2 tags, that is, Tag-A and Tag-B is presented in
Table 3.

Tag-A covers the frequency band 3.3–13.5 GHz, whereas
the total bandwidth of the tag is 10.2 GHz.

The RF range for Tag-B, that is analysed using Rogers RT/
duroid/5880 flexible substrate, is 3.5–14.0 GHz and the overall

**FIGURE 2** Twenty-seven-bit chipless RFID tag design

**FIGURE 3** A, RCS response of Tag-A. B, RCS response of Tag-B

<table>
<thead>
<tr>
<th>Slot name</th>
<th>Slot width (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A1-A4</td>
<td>0.21</td>
</tr>
<tr>
<td>B1-B3</td>
<td>0.27</td>
</tr>
<tr>
<td>C1-C4</td>
<td>0.26</td>
</tr>
<tr>
<td>All other slots</td>
<td>0.3</td>
</tr>
</tbody>
</table>
bandwidth is 10.5 GHz. This shows that the displacement of the substrate from rigid to flexible shifts the frequency band towards the right and the operational bandwidth increases.

Figure 4 shows the measured and computed results of Tag-A along with its prototype. It can be seen that the measured and computed response of the tag displays an acceptable agreement. A slight drift along the frequency axis is observed for some resonant dips which are easily detectable with the reader setup.

The surface induced current patterns at 2 different frequencies, using Rogers RT/duroid/5870 substrate is depicted in Figure 5. The Figure 5A shows the surface current distribution at the lowest frequency, whereas, the Figure 5B presents the mapping of the induced current at the highest frequency.

Each slot gives 1 dip on a distinct resonant frequency. When the tag is excited with an incident plane wave, a particular tag ID is generated. Each slot in the structure corresponds to a logic state ‘1’. For shifting the logic state from ‘1’ to ‘0’, the slot can either be shorted or removed completely. Hence, the shorted or removed slot will not give any dip at a particular resonant frequency and will correspond to ‘0’ logic state. Every slot has a different frequency response; hence, shorting any slot will have a very little effect on the frequency response of the nearby slots. By integrating this approach, many Auto-Tag IDs can be formed as shown in Figure 6. Consequently, a unique tag ID can be generated for each particular tag which will result in avoidance of collisions within the network.

### 4.1 Humidity sensor

The 27-bit passive chipless RFID tag shows the functionality of humidity sensing when polyamide sheet is integrated into the design.

The prototype is designed by etching the copper radiators on Rogers RT/duroid/5870. The humidity sensing is achieved by placing a DuPont Kapton HN heat resistant conformal tape on the shortest slot and the metal portion corresponding to the respective slot, as shown in Figure 7.

Hence, the last bit obtained due to the shortest slot depicts the sensing bit. The thickness of Kapton HN is 125 μm with a relative permittivity of 3.5. The resonant frequency of the sensing bit shifts slightly towards the left side

### TABLE 3

Comparative study of Tag-A and Tag-B

<table>
<thead>
<tr>
<th>Characteristics</th>
<th>Tag-A</th>
<th>Tag-B</th>
</tr>
</thead>
<tbody>
<tr>
<td>Substrate</td>
<td>Rogers RT/duroid /5870</td>
<td>Rogers RT/duroid /5880</td>
</tr>
<tr>
<td>Thickness (mm)</td>
<td>0.78</td>
<td>0.508</td>
</tr>
<tr>
<td>Permittivity</td>
<td>2.2</td>
<td>2.2</td>
</tr>
<tr>
<td>Loss tangent</td>
<td>0.0009</td>
<td>0.0009</td>
</tr>
<tr>
<td>Radiator</td>
<td>Copper</td>
<td>Copper</td>
</tr>
<tr>
<td>Bandwidth (GHz)</td>
<td>10.2</td>
<td>10.5</td>
</tr>
<tr>
<td>Freq. band (GHz)</td>
<td>3.3–13.5</td>
<td>3.5–14.0</td>
</tr>
<tr>
<td>Flexibility</td>
<td>-</td>
<td>✓</td>
</tr>
</tbody>
</table>

**FIGURE 4** Measured and computed RCS response of Tag-A

**FIGURE 5** A, Current distribution at lowest frequency (3.3 GHz).
B, Current distribution at highest frequency (13.5 GHz)
with the steady increase in the moisture level. This is because the Kapton HN sheet used for sensing purpose can absorb the moisture. Thus, the novelty of the design lies in the fact that it does not require any external circuit for sensing. Figure 8 shows the RCS feedback with Kapton HN expressed as ‘Tag-C’.

The 27-bit chipless humidity sensor tag illustrates a reliable performance. Five prototypes of the proposed tag have been tested. The tag exhibits 0.25% tolerance in RCS values whereas 0.3% tolerance is monitored in the required frequency band as shown in Figure 9.

The proposed tag is responsive to moisture present in the environment. It is experimentally analysed using climate chamber by Weiss Technik WK11–180.30 The sensing characteristics are scrutinized by implementing diverse levels of moisture in the chamber. The Figure 10 shows that for every 15% increase in the moisture, the RF response of the respective tag shows a subtle drift towards left side, that is, the lower frequencies.

4.2 | Temperature sensor

The proposed chipless tag design possesses the functionality of temperature sensing. Temperature sensing can be attained using polymer resins. The dielectric permittivity of these polymer materials alters at high frequencies and are temperature dependant. As the temperature increases, the dielectric properties of polymer resins also increase. Some commonly used polyamide materials are Stanyl, Zenite, Valox, and Zytel.

In the proposed research, temperature sensing is achieved using Stanyl. A linear performance of increasing dielectric permittivity is depicted with temperature.31 On increasing the temperature from 25°C to 125°C, the dielectric permittivity of Stanyl polymer changes from 3.5–3.8. The substrate is a fusion of Rogers RT/duroid/5870 and Stanyl polyamide resin as shown in Figure 11.19 Stanyl polymer is deployed
beneath the shortest slot which gives the dip at the highest frequency. This slot is referred as ‘sensing slot’.

During the measurement phase, the sensor tag and reader antenna are placed inside environmental chamber namely Weiss Technik WK11–180. The sensing response of the last bit is shown in Figure 12. The response justifies that with increasing temperature from 25°C to 125°C; the material properties of Stanyl polyamide changes which result in a slight shift of the last bit, that is, the sensing bit, towards lower frequencies. Hence, temperature sensing is achieved using a combination of 2 substrates, that is, Rogers RT/duroid/5870 and Stanyl polymer.

5 | CONCLUSION

A finite-sized, data dense, fully passive, chipless RFID tag has been proposed. The tag is excited by a linearly polarized plane wave. This cost-effective tag has the ability to generate 2^27 unique Auto tag IDs. The circular shaped radiators of copper, loaded with slots are analysed for 2 different substrates; Rogers RT/duroid/5870 and Rogers RT/duroid/5880 flexible within the restricted tag dimension of 23 × 23 mm². The formulated tag is not only capable of beholding high data capacity but it also offers the additional functionalities of humidity and temperature sensing without requiring any external circuitry. The tag presented in this research article has various advantages which include compactness, robustness, low-cost, sensing, and flexibility, and it can function at a wide range of incident angles. Hence, the temperature and humidity sensor tags can be used in the monitoring and tracking of humidity and temperature sensitive products such as in pharmaceutical industry.

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